How to....

Connect Bluetooth device to the Trans-receiver

- Match the Pins on Bluetooth with the markings on Trans-receiver.
- Align the pins of Bluetooth with the sockets on Trans-receiver.
- Push the pins in the socket carefully.
- Bluetooth will be stand perpendicular to the Trans-receiver PCB.



- Use wires provided to connect the Motors to the Trans-receiver.
- Trans-receiver has pair of male pins for each motor indicated as Left Motor, Right Motor, Motor 3 and Motor 4.
- Left and Right motor pins are to be used for the motors used to move the vehicle platform.
- These motors are **controlled in pair** to move forward, backward and turn.



- Use Motor 3 and Motor 4 pins for additional motors used in your Robot.
- Do not bend the sockets while inserting or removing the wires from the pins.

Connect Power Supply to the Trans-receiver

- 9 12 V power supply can be connected to the Trans-receiver.
- The kit is provided with 6 AA cell battery holder.
- The DC plug of the battery holder should be connected to the Power Supply socket provided on the Trans-receiver PCB.
- Trans-receiver PCB has a low voltage indicator LED which starts blinking when the voltage drops below 7.5 volts.



Install Qurio Kindle Remote Control App on Android Phone

- Download the QurioKindle.apk file from the CD onto your Android Phone.
- Open the QurioKindle.apk from your phone.
- Install the App.
- Your App is ready to use.

* Android App is also available for download at <u>www.quriousmind.com/qurio-kindle.html</u>

Pairing Android Phone with Qurio Kindle

- Power up Qurio Kindle Trans-receiver.
- Turn on Bluetooth of your phone.
- Scan for Bluetooth devices in your phone.
- Select the device ending with HC-05 from your Bluetooth Device list.
- You will be prompted for a Password.
- Enter the password provided inside the Qurio Kindle box.
- Your phone is now paired with Qurio Kindle.

Use Qurio Kindle App

- Open Qurio Kindle App.
- Click on Remote Control button to go to Remote Control screen.
- Initially only Connect button will be enabled.
- Click on Connect button. You will be presented with the list of all devices paired with your Android phone.



- Select the Device ending with HC-05 from the list (same device which was paired in earlier step).
- After successful connection, the Connect button will be disabled and Disconnect button and all other buttons on the remote control screen will be enabled.
- The Remote is divided into two parts.
- Right side controls Left and Right Motor together; used to control Vehicle platform.
- The upper half moves the Vehicle Platform in Forward direction and the lower half moves the Vehicle platform in reverse direction.
- The left side controls additional motors 3 and 4 if used.
- Click on Disconnect button before exiting the App.



Trouble Shooting

My Robot reverses if I press the Forward buttons on the App and vice versa

- Check if you have connected Left Motor of the Robot to the Right Motor on the Receiver and vice versa. Correct the same.
- If the problem persists, change the polarity of the connection by reversing the wires at the receiver end (exchange the Black and Red wire positions) for both motors.

My Robot turns when I press the Forward or Reverse buttons on the App

 Change the polarity of Left and Right Motors (by reversing the wires of that motor at the receiver end) one by one.

My Bluetooth is not getting connected even after repeated tries

- Check if you have connected the Bluetooth Module correctly.
- Switch off the power from the Trans-receiver and switch it on again.
- Turn OFF and Turn ON Bluetooth of your phone.